

Graduate Macroeconomic Theory (ECN 200E)

Discussion Section Week 2

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Stochastic Growth Model

Key Components:

- Objective: Maximize lifetime utility

$$V(A, k) = \max_{\{c_t, k_{t+1}\}} \mathbb{E}_0 \left[\sum_{t=0}^{\infty} \beta^t u(c_t) \right]$$

subject to:

$$c_t + k_{t+1} = A_t k_t^{\alpha}, \quad k_{t+1} \geq 0.$$

- Law of motion for productivity:

$$A_{t+1} \sim F(A_{t+1} | A_t).$$

Euler Equation

The first-order condition for the optimization problem is:

$$u'(c_t) = \beta \mathbb{E}_t \left[u'(c_{t+1}) \cdot (\alpha A_{t+1} k_{t+1}^{\alpha-1} + 1 - \delta) \right].$$

The solution requires:

- A policy function $k_{t+1} = g(A_t, k_t)$,
- A value function $V(A, k)$ satisfying the Bellman equation.

Guess and Verify: Policy Function

Guess: Policy function for capital:

$$k_{t+1} = \lambda A_t k_t^\alpha.$$

Steps to Verify:

- 1 Substitute the guess into the resource constraint:

$$c_t = (1 - \lambda) A_t k_t^\alpha.$$

- 2 Compute marginal utility:

$$u'(c_t) = \frac{1}{(1 - \lambda) A_t k_t^\alpha}.$$

- 3 Substitute into the Euler equation and simplify.
- 4 Solve for λ : $\lambda = \beta\alpha$.

Result: The policy function is:

$$k_{t+1} = \beta\alpha A_t k_t^\alpha.$$

Guess and Verify: Value Function

Guess: Value function of the form:

$$V(A, k) = D + E \log(k) + F \log(A),$$

where D, E, F are constants to be determined.

Steps to Verify:

- 1 Substitute the guess into the Bellman equation:

$$V(A, k) = \max_{k'} \{ u(c) + \beta \mathbb{E} [V(A', k')] \}.$$

- 2 Compute:

$$c = Ak^\alpha - k', \quad u(c) = \log(c).$$

- 3 Derive the optimal k' and substitute back into $V(A, k)$.

Why This Functional Form?

- Preferences: $u(c) = \log c$
- Technology: $y = Ak^\alpha$
- Resource constraint implies c is proportional to Ak^α

Key implication:

$$\log c = \text{constant} + \log A + \alpha \log k$$

Intuition: Utility, production, and consumption are all log-linear in states.

Why Does the Bellman Equation Close?

Guess:

$$V(A, k) = D + E \log k + F \log A$$

Bellman equation:

$$V(A, k) = \max_{k'} \{ \log c + \beta E[V(A', k')] \}$$

- $\log c$ is linear in $\log k$ and $\log A$
- $E[V(A', k')]$ preserves log-linearity
- RHS has the same functional form as the guess

Result: Only the coefficients (D, E, F) need to be determined.

Why Is This a Special Case?

- Requires log utility
- Requires Cobb–Douglas technology
- Requires simple capital accumulation
- Requires no constraints or nonlinearities

If any of these break:

- The Bellman equation no longer preserves the guessed form
- Additional nonlinear terms appear
- Guess and verify fails

Conclusion: Guess and verify works only in knife-edge cases.

Conclusion

Key Results:

- **Policy Function:**

$$k_{t+1} = \beta\alpha A_t k_t^\alpha.$$

- **Value Function:**

$$V(A, k) = D + \frac{\alpha}{1 - \beta\alpha} \log(k) + \frac{1}{1 - \beta\alpha} \log(A).$$

These results verify the functional forms for the policy and value functions under the stochastic growth model.

Taylor Expansion: The Basics

Taylor Series Expansion

For a function $f(x)$, the Taylor expansion around a point x_0 is:

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 + \dots$$

Linear Approximation (First-Order)

$$f(x) \approx f(x_0) + f'(x_0)(x - x_0)$$

Linearization Method

1. Special Case: Multiplicative Equation (log-separable)

$$y_t = k_t^\alpha (a_t n_t)^{1-\alpha}$$

Linearization Method 1: Log-Linearization

Step 1: Take logs and Subtract the steady state

$$\ln y_t = \alpha \ln k_t + (1 - \alpha)(\ln a_t + \ln n_t)$$

Step 2: Express in deviations from steady state

$$\ln \frac{y_t}{\bar{y}} = \alpha \ln \frac{k_t}{\bar{k}} + (1 - \alpha) \left(\ln \frac{a_t}{\bar{a}} + \ln \frac{n_t}{\bar{n}} \right)$$

Key approximation

$$\ln \frac{x_t}{\bar{x}} = \ln \left(1 + \frac{x_t - \bar{x}}{\bar{x}} \right) \approx \frac{x_t - \bar{x}}{\bar{x}} \equiv \hat{x}_t$$

Result (log-linear form)

$$\hat{y}_t = \alpha \hat{k}_t + (1 - \alpha)(\hat{a}_t + \hat{n}_t)$$

Linearization Method 2: Total Differentiation

Step 1: Total differentiation

$$dy_t = \left. \frac{\partial y}{\partial k} \right|_{\bar{k}, \bar{a}, \bar{n}} dk_t + \left. \frac{\partial y}{\partial a} \right|_{\bar{k}, \bar{a}, \bar{n}} da_t + \left. \frac{\partial y}{\partial n} \right|_{\bar{k}, \bar{a}, \bar{n}} dn_t$$
$$dy_t = \alpha \bar{k}^{\alpha-1} (\bar{a} \bar{n})^{1-\alpha} dk_t + (1-\alpha) \bar{k}^{\alpha} \bar{a}^{-\alpha} \bar{n}^{1-\alpha} da_t + (1-\alpha) \bar{k}^{\alpha} \bar{a}^{1-\alpha} \bar{n}^{-\alpha} dn_t$$

Key identity

$$\frac{dx_t}{x_t} = \frac{x_t - \bar{x}}{\bar{x}} \equiv \hat{x}_t \quad \Rightarrow \quad dx_t = \bar{x} \hat{x}_t$$

Step 2: Divide by y_t

$$\frac{dy_t}{y_t} = \alpha \frac{dk_t}{k_t} + (1-\alpha) \left(\frac{da_t}{a_t} + \frac{dn_t}{n_t} \right)$$

Linearization Method

2. General Case

$$\frac{1}{c_t} = \beta \mathbb{E}_t \left[\frac{1}{c_{t+1}} r_{t+1} \right]$$
$$r_{t+1} = \alpha a_{t+1} k_{t+1}^{\alpha-1} + (1 - \delta)$$

Linearizing Euler Equation (1/2)

The household Euler equation is:

$$\frac{1}{c_t} = \beta E_t \left[\frac{1}{c_{t+1}} r_{t+1} \right]$$

Totally differentiate the Euler equation:

$$-\frac{1}{\bar{c}^2} dc_t = \beta E_t \left[-\frac{\bar{r}}{\bar{c}^2} dc_{t+1} + \frac{1}{\bar{c}} dr_{t+1} \right] \quad (1)$$

$$-\hat{c} = \beta r E_t [-\hat{c}_{t+1} + \hat{r}_{t+1}] \quad (2)$$

At the steady state:

$$\frac{1}{\bar{c}} = \beta \frac{1}{\bar{c}} \bar{r} \quad \Rightarrow \quad \beta \bar{r} = 1$$

Linearizing Euler Equation (2/2)

Rearranging terms:

$$\hat{c}_t = E_t \hat{c}_{t+1} - E_t \hat{r}_{t+1}$$

Interpretation:

- Consumption is forward-looking
- Expected returns shift consumption across time

Linearizing Return on Capital (1/2)

The gross return on capital is:

$$r_{t+1} = \alpha a_{t+1} k_{t+1}^{\alpha-1} + (1 - \delta)$$

Totally differentiate:

$$dr_{t+1} = \alpha(\alpha - 1)\bar{a}\bar{k}^{\alpha-2}dk_{t+1} + \alpha\bar{k}^{\alpha-1}da_{t+1}$$

Divide by $\bar{r}$:

$$\hat{r}_{t+1} = \frac{\alpha\bar{a}\bar{k}^{\alpha-1}}{\bar{r}} \left[\hat{a}_{t+1} + (\alpha - 1)\hat{k}_{t+1} \right]$$

Linearizing Return on Capital (2/2)

At the steady state:

$$\bar{r} = \bar{\alpha} \bar{k}^{\alpha-1} + (1 - \delta)$$

$$\therefore \hat{r}_{t+1} = \frac{\alpha \bar{\alpha} \bar{k}^{\alpha-1}}{\bar{\alpha} \bar{k}^{\alpha-1} + (1 - \delta)} \left[\hat{a}_{t+1} - (1 - \alpha) \hat{k}_{t+1} \right]$$

Linearization Example ¹

Labor Supply Equations:

- When $\epsilon = 0$:

$$\eta N_t^{\eta-1} = w_t$$

- When $\epsilon = 1$:

$$\eta N_t^{\eta-1} \frac{1}{(1 - N_t)\lambda_t} = w_t,$$

where $\frac{1}{C_t} = \lambda_t$ is the marginal utility of consumption.

Question: Linearize the two labor supply conditions above.

Code example: What Model Are We Solving?

We solve a **stochastic growth model** with full depreciation.

Preferences:

$$\max_{\{c_t, k_{t+1}\}} \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t \log c_t$$

Technology:

$$y_t = z_t A k_t^{\alpha}$$

Resource constraint:

$$c_t + k_{t+1} = z_t A k_t^{\alpha}$$